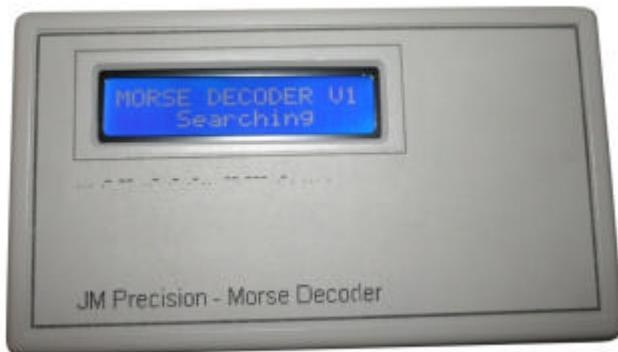


JM Precision

MORSE CODE DECODER

Serial Data Link and Internal Data Storage



USER MANUAL

Revision 2

www.jmprecision.co.uk

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Introduction

The JM Precision Morse Decoder is used to decode Morse code audio signals and to display the decoded text along with the actual received code on a continuously scrolling display.

A direct connection to the unit is not required as it has a built in microphone and simply needs to be positioned in front of a receiver which is tuned to a station which is transmitting Morse code.

This unit has built in data memory that stores the decoded text which can then be downloaded to a PC via a serial or USB link (using a suitable adaptor) and saved to a text file.

The decoder can also be connected to a PC during decoding operation allowing the decoded text to be displayed and saved on the PC in real time.

The memory store is non volatile so the data is not lost when the unit is turned off.

A comprehensive set of serial commands gives access to a number of setup options allowing the unit to be configured to your preference.

There are many on-line resources where Morse recordings can be downloaded and decoded using this device.

Operation

Battery Insertion

- 1 Move the power switch to the off position
- 2 Remove the battery compartment cover located on the rear of the unit.
- 3 Remove the old battery if fitted.
- 4 Connect the new battery and slot it into the battery compartment
- 5 Refit the battery compartment cover

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Calibration

Before the unit will operate it must be calibrated. This operation is performed automatically after switching the unit on but should be repeated when required.

To allow the unit to properly calibrate

- 1 Tune your radio to a station so that the Morse can be clearly heard.
- 2 Switch on the decoder and place it in a location where it will pick up the audio sounds.
- 3 Immediately after switching on the decoder will display 'initialising' for around two seconds.
During this period the unit is preparing to perform a calibration and you must ensure that the unit is positioned before the end of this period.
- 4 After around two seconds the display will change to 'searching'
The unit is now searching for Morse data in the audio signals with which to calibrate itself. It is important that it can clearly 'hear' the sound so the unit should not be moved when the word 'searching' is displayed as this can cause the calibration to fail.
The reason it needs to perform this calibration is due to the huge range of Morse sending speeds. The calibration procedure ensures that the unit can properly decode signals being sent at the currently received speed.

If the unit fails to calibrate successfully then try to reposition it or adjust the audio volume and reset the unit by switching it off and then back on again.

During calibration the unit may display an exclamation character '!' at the left of the lower line.

This indicates that the Morse keying is non standard, odd relationships between dots, dashes and spaces, but it will continue to attempt to decode the data.

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Data Display

Once successfully calibrated the decoded text should start to appear on the display.

If you change stations and the speed of the code is significantly different then you should reset the unit and allow it to recalibrate.

Loud noises after calibration may cause errors in the decoding but the unit will continue decoding normally once the noise has stopped.

Any characters that are decoded that the unit does not recognise are displayed as

'#'

If you are getting many of these in the displayed text then try adjusting the volume or recalibrating the unit as described above. Also note that noisy audio signals can cause poor decoding.

At very low Morse rates, typically below 12 words per minute the unit may be unable to determine the difference between character spacing and word spacing. This will cause the characters to be spaced as if they are all individual words. It is however unlikely that you will find such slow speeds in use by any commercial operators.

Should the display become dim or the unit fail to decode any signals then the battery should be replaced.

Sample Morse recordings can be downloaded from our website at
www.jmprecision.co.uk

Low Battery Warning

If the internal battery voltage drops too low then the message Low Battery!

Will appear on the display bottom line and the backlight will be set to its lowest brightness to save power.

The unit will attempt to continue decoding but you should replace the battery as soon as possible.

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Serial Operation

The decoder can be connected to PC to allow both capture of decoded text and remote control of the units' settings.

Connect the decoder to a PC using a standard RS232 serial cable or RS232 to USB adaptor.

In order to capture the data from the unit and send control commands you will require a serial communications application. Many are commercially available but most computers have Hyper Terminal installed so we will assume that is being used here.

Start Hyper Terminal and enter a name for the new connection in the dialog that appears.

Next select the COM port that you have connected the decoder to.

Select a Bits per second speed (Baud) rate of 9600.

Data bits 8

Parity None

Stop bits 1

Flow control None

Click OK and the Hyper terminal window appears.

The data from the unit will appear in this unit and commands typed into this window will be sent to the unit. See the serial commands section for details on the commands that the unit will respond to.

Switch on the decoder and you should see the message

JM Precision Morse Decoder Version x.xx

Where x.xx is the firmware revision number

Appear in the Hyper Terminal window.

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Serial Commands

The following table lists the supported Serial commands. To send a command first make sure that the Hyper Terminal window is selected and then type in the command followed by the Enter key.

Note that the commands are all uppercase and will not appear in the data window unless you have turned on the Hyper Terminal 'Echo typed commands locally' option. Other commands are ignored.

Commands marked * are factory default settings.

RS 232 Commands		
Command	Description	Returned value
CLR	Clear RAM chip data	OK
SND	Download Stored data	Stored Text Data
BLF	Turn off the display backlight	OK
BL1*	Set the backlight to brightness 1	OK
BL2	Set the backlight to brightness 2	OK
BL3	Set the backlight to brightness 3	OK
BL4	Set the backlight to brightness 4	OK
DCN*	Decoding on	OK
DCF	Decoding off	OK
CAL	Restart decoding calibration	OK
ACN*	Automatic calibration at start up on	OK
ACF	Automatic calibration at start up off	OK
BAT	Measure battery voltage	Battery voltage
VER	Report current firmware version	Firmware Version
RAM	Report memory capacity (KB)	Memory capacity
RST	Restore factory defaults	OK
POR	Perform a full power on reset	OK
TMN	Fast timing on	OK
TMF*	Fast timing off (normal timing)	OK
DOT	Report current Dot length	Dot length
TSN*	Show Dot length at start	OK
TSF	Do not show Dot length at start	OK
LFN	Format text output	OK
LFF*	Do not format text output	OK
CFG	Report all configuration information	Configuration

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Internal Memory Capacity

The following table indicates the approximate number of decoded words that each memory capacity option will store.

Memory Storage capacity	
Memory Size	Word storage capacity (approx)
16kB	300
64kB	1200
128kB	2400
256kB	4800

The internal memory is arranged as a circular buffer so that data is saved continually and the oldest data is over written by new data.

Character Set

The following table shows the character set supported by the decoder.

Character Set							
A	B	C	D	E	F	G	H
I	J	K	L	M	N	O	P
Q	R	S	T	U	V	W	X
Y	Z	0	1	2	3	4	5
6	7	8	9	:	;	-	"
()	?	.	=	/	,	+
-	'						

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Specification

Length	145mm
Depth	80mm
Height	35mm
Weight (without battery)	175g
Power	9V battery PP3 (6LR61)
Maximum current	30mA
Display	2 line LCD white on blue with backlight
Maximum bit rate	30 bits / second
Maximum Morse rate	60 words per minute (nominal)
Minimum Morse rate	5 words per minute (nominal)
RS232	9600baud – 8 – 1 – 0
Internal RAM	16kB – 256kB (options)